

# Explicit Upper Bounds for Dual Norms of Residuals

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## Background

A posteriori error estimation consists of two steps:

- ▶ Prove the equivalence of the primal norm of the error and of the dual norm of the residual.
- ▶ Derive easily computable error indicators that yield upper and lower bounds for the dual norm of the residual.

## Goal

Derive upper bounds for dual norms of residuals which are:

- ▶ fully explicit,
- ▶ guaranteed,
- ▶ robust.

## Tools

- ▶ Decomposition of the residual into a regular and singular part. (**element** and **jump residuals**)
- ▶ Partition of unity based on the nodal shape functions.
- ▶ Trace inequalities with explicit constants.
- ▶ Poincaré inequalities with explicit constants.

Resumé: **Reduce everything to Poincaré inequalities for convex domains.**

## Domain and Norms

- ▶  $\Omega \subset \mathbb{R}^d$  open, bounded, connected
- ▶  $\Gamma_D$  Dirichlet boundary
- ▶  $\mu_d, \mu_{d-1}$  Lebesgue measures on  $\mathbb{R}^d$  and  $\mathbb{R}^{d-1}$
- ▶  $L^p(\Omega)$  and  $\|\cdot\|_{L^p(\Omega)}$  standard Lebesgue space and norm
- ▶  $W^{1,p}(\Omega)$  standard Sobolev space equipped with  $\|\cdot\|_{L^p(\Omega)}$
- ▶  $W^{-1,p'}(\Omega)$  dual space equipped with

$$\|\cdot\|_{W^{-1,p'}(\Omega)} = \sup\{\langle \cdot, v \rangle : \|\nabla v\|_{L^p(\Omega)} = 1\}$$

## Partition and Finite Element Spaces

- ▶  $\mathcal{T}$  affine equivalent, admissible partition, **may be anisotropic**
- ▶  $\mathcal{N}, \mathcal{E}$  vertices and faces corresponding to  $\mathcal{T}$
- ▶  $\Sigma$  skeleton (union of all faces) of  $\mathcal{T}$
- ▶  $S^{1,0}(\mathcal{T}), S_D^{1,0}(\mathcal{T})$  standard lowest order conforming finite element spaces
- ▶  $\lambda_z, z \in \mathcal{N}$ , standard lowest order nodal shape functions
- ▶  $\omega_z, \sigma_z$  union of all elements resp. faces with vertex  $z$
- ▶  $\mu_{d,z}, \mu_{d-1,z}, L_z^p, \|\cdot\|_{L_z^p(\Omega)}$  measures, spaces and norms with weight  $\lambda_z$ , i.e.

$$\|v\|_{L_z^p(\Omega)}^p = \int_{\Omega} |v|^p \lambda_z$$

## Residual

$R \in W^{-1,p'}(\Omega)$  given residual satisfying:

- ▶  $R$  has an  $L^p$ -representation

$$\langle R, v \rangle = \int_{\Omega} rv + \int_{\Sigma} jv.$$

- ▶  $R$  vanishes on  $S_D^{1,0}(\mathcal{T})$ .

## Localization

- ▶  $\lambda_z, z \in \mathcal{N}$ , form a partition of unity:

$$\langle R, v \rangle = \sum_{z \in \mathcal{N}} \langle R, \lambda_z v \rangle, \quad \|\nabla v\|_{L^p(\Omega)}^p = \sum_{z \in \mathcal{N}} \|\nabla v\|_{L_z^p(\omega_z)}^p$$

- ▶  $v_z \in \mathbb{R}$  arbitrary subject to the condition  $\lambda_z v_z \in S_D^{1,0}(\mathcal{T})$ :

$$\langle R, \lambda_z v \rangle = \langle R, \lambda_z(v - v_z) \rangle$$

- ▶  $L^p$ -representation of  $R$ :

$$\langle R, \lambda_z(v - v_z) \rangle = \int_{\omega_z} r \lambda_z(v - v_z) + \int_{\sigma_z} j \lambda_z(v - v_z)$$

## Basic Poincaré-type Inequalities

For every vertex  $z \in \mathcal{N}$  there are constants  $c_p(\omega_z)$ ,  $c_p(\sigma_z)$  and  $v_z \in \mathbb{R}$  with  $\lambda_z v_z \in S_D^{1,0}(\mathcal{T})$  and:

$$\begin{aligned} \|v - v_z\|_{L_z^p(\omega_z)} &\leq c_p(\omega_z) h_z \|\nabla v\|_{L_z^p(\omega_z)} \\ \left\{ \sum_{E \subset \sigma_z} h_E^{\frac{1}{p}} \|v - v_z\|_{L_z^p(E)}^p \right\}^{\frac{1}{p}} &\leq c_p(\sigma_z) h_z \|\nabla v\|_{L_z^p(\omega_z)} \end{aligned}$$

with  $h_z$  the diameter of  $\omega_z$  and  $h_E^{\frac{1}{p}} = \mu_{d,z}(\omega_E) / \mu_{d-1,z}(E)$ .

## Vertex Oriented A Posteriori Error Estimate

Set

$$\begin{aligned} \eta_z &= h_z \left[ c_p(\omega_z) \|r\|_{L_z^{p'}(\omega_z)} \right. \\ &\quad \left. + c_p(\sigma_z) \left\{ \sum_{E \subset \sigma_z} (h_E^{\frac{1}{p}})^{1-p'} \|j\|_{L_z^{p'}(E)}^{p'} \right\}^{\frac{1}{p'}} \right] \end{aligned}$$

then

$$\|R\|_{W^{-1,p'}(\Omega)} \leq \left\{ \sum_{z \in \mathcal{N}} \eta_z^{p'} \right\}^{\frac{1}{p'}}.$$

## Element Oriented A Posteriori Error Estimate

Set

$$\begin{aligned} c_p(K) &= \max_{z \in \mathcal{N}_K} \left\{ c_p(\omega_z) \frac{h_z}{h_K} \right\}, \\ c_p(E) &= \max_{z \in \mathcal{N}_E} \left\{ c_p(\sigma_z) \frac{h_z}{h_E^{\frac{1-p'}{p}} (h_E^{\frac{1}{p}})^{\frac{1}{p'}}} \right\} \end{aligned}$$

then

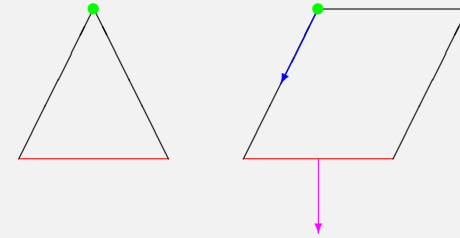
$$\begin{aligned} \|R\|_{W^{-1,p'}(\Omega)} &\leq \left\{ \sum_{K \in \mathcal{T}} c_p(K)^{p'} h_K^{p'} \|r\|_{L^{p'}(K)}^{p'} \right\}^{\frac{1}{p'}} \\ &\quad + \left\{ \sum_{E \in \mathcal{E}} c_p(E)^{p'} h_E \|j\|_{L^{p'}(E)}^{p'} \right\}^{\frac{1}{p'}}. \end{aligned}$$

## Typical Values of Constants

	$\omega_z$ convex		$\omega_z$ not convex	
	$z \notin \Gamma_D$	$z \in \Gamma_D$	$z \notin \Gamma_D$	$z \in \Gamma_D$
$c_p(\omega_z)$	0.3	1.0	0.7	2.0
$c_p(\sigma_z)$	0.7	1.7	1.4	3.4
$c_p(K)$	0.7	2.2	$1.4\lambda$	$4.1\lambda$
$c_p(E)$	$2.4\sqrt{\lambda}$	$5.5\sqrt{\lambda}$	$5.8\sqrt{\lambda}$	$13.5\sqrt{\lambda}$

where  $\lambda$  measures the anisotropy

## Vector Field



## Vector Field

The vector field

$$\gamma_{K,E} = \begin{cases} x - a_{K,E} & \text{if } K \text{ is a simplex,} \\ \frac{(x - a_{K,E}) \cdot n_{K,E}}{m_{K,E} \cdot n_{K,E}} m_{K,E} & \text{if } K \text{ is a parallelepiped,} \end{cases}$$

has the properties:

$$\operatorname{div} \gamma_{K,E} = \nu_K = \begin{cases} d & \text{if } K \text{ is a simplex,} \\ 1 & \text{if } K \text{ is a parallelepiped,} \end{cases}$$

$$\gamma_{K,E} \cdot n_K = 0 \quad \text{on } \partial K \setminus E,$$

$$\gamma_{K,E} \cdot n_K = \frac{\nu_K \mu_d(K)}{\mu_{d-1}(E)} \quad \text{on } E,$$

$$\|\gamma_{K,E}\|_{L^\infty(K)} \leq h_K.$$

## Trace Identity

The Gauß theorem applied to  $w\gamma_{K,E}$  and  $\lambda_z w\gamma_{K,E}$  yields:

$$\begin{aligned} \frac{1}{\mu_{d-1}(E)} \int_E w &= \frac{1}{\mu_d(K)} \int_K w \\ &\quad + \frac{1}{\nu_K \mu_d(K)} \int_K \gamma_{K,E} \cdot \nabla w, \\ \frac{1}{\mu_{d-1,z}(E)} \int_E \lambda_z w &= \frac{1}{\mu_{d,z}(K)} \int_K \lambda_z w \\ &\quad + \frac{1}{(\nu_K + 1) \mu_{d,z}(K)} \int_K \lambda_z \gamma_{K,E} \cdot \nabla w. \end{aligned}$$

## Trace Inequalities

The trace identity applied to  $|u|^q$  yields:

$$\begin{aligned} \frac{1}{\mu_{d-1,z}(E)} \|u\|_{L_z^q(E)}^q &\leq \frac{1}{\mu_{d,z}(K)} \|u\|_{L_z^q(K)}^q \\ &+ \frac{qh_K}{(\nu_K + 1)\mu_{d,z}(K)} \|u\|_{L_z^q(K)}^{q-1} \|\nabla u\|_{L_z^q(K)}. \end{aligned}$$

The above trace inequality applied to the elements in  $\omega_z$  and their faces gives:

$$\begin{aligned} \sum_{E \subset \sigma_z} h_E^\perp \|u\|_{L_z^q(E)}^q &\leq d \|u\|_{L_z^q(\omega_z)}^q \\ &+ d \max_{K \subset \omega_z} \frac{qh_K}{\nu_K + 1} \|u\|_{L_z^q(K)}^{q-1} \|\nabla u\|_{L_z^q(K)}. \end{aligned}$$

## Contribution of the Skeleton

The trace inequality for  $\sigma_z$  implies:

$$\begin{aligned} c_p(\sigma_z) &\leq c_p(\omega_z) \left\{ d \left[ 1 + \frac{p}{c_p(\omega_z)} \max_{K \subset \omega_z} \frac{h_K}{(\nu_K + 1)h_z} \right] \right\}^{\frac{1}{p}} \\ &\leq \left\{ d \left[ 1 + \frac{p}{2} \right] \right\}^{\frac{1}{p}} \max \left\{ c_p(\omega_z), c_p(\omega_z)^{1-\frac{1}{p}} \right\}. \end{aligned}$$

## Tasks

We must bound

- ▶  $c_p(\omega_z)$  for  $z \in \Gamma_D$  (**Friedrich's inequality**),
- ▶  $c_p(\omega_z)$  for  $z \notin \Gamma_D$  and **convex**  $\omega_z$ ,
- ▶  $c_p(\omega_z)$  for  $z \notin \Gamma_D$  and **non-convex**  $\omega_z$ .
- ▶ Set

$$C_{P,p}(\omega_z) = \sup_{u \in W^{1,p}(\omega_z)} \inf_{c \in \mathbb{R}} \frac{\|u - c\|_{L_z^p(\omega_z)}}{h_z \|\nabla u\|_{L_z^p(\omega_z)}}.$$

## Vertices on the Dirichlet Boundary

The trace inequality for elements and faces yields for all **Dirichlet vertices**

$$\begin{aligned} c_p(\omega_z) &\leq \left[ 1 + M_z \max_{E \subset \Gamma_{D,z}} \left( \frac{h_z^\perp}{h_E^\perp} \right)^{\frac{1}{p}} \right] C_{P,p}(\omega_z) \\ &+ M_z \max_{E \subset \Gamma_{D,z}} \left[ \frac{h_{\omega_E}}{h_z(\nu_{\omega_E} + 1)} \left( \frac{h_z^\perp}{h_E^\perp} \right)^{\frac{1}{p}} \right] \end{aligned}$$

where  $M_z \leq \max_{K \subset \omega_z} (d + 1 - \nu_K)$  is the maximal number of Dirichlet faces per element,  $\Gamma_{D,z} = \Gamma_D \cap \partial\omega_z$  and  $h_z^\perp = \mu_{d,z}(\omega_z) / \mu_{d-1,z}(\Gamma_{D,z})$ .

## Convex Domains

If  $\omega_z$  is **convex** a result of Chua and Wheeden implies

$$C_{P,p}(\omega_z) \leq \bar{C}_{P,p} \leq \begin{cases} \frac{1}{2} & \text{for } p = 1, \\ \frac{1}{\pi} & \text{for } p = 2, \\ 2\left(\frac{p}{2}\right)^{\frac{1}{p}} & \text{for general } p. \end{cases}$$

## Non-Convex Domains

If  $\omega_z$  is **not convex** we have

$$C_{P,p}(\omega_z) \leq 4\bar{C}_{P,p}(n_z - 1)^{1-\frac{1}{p}} \left[ \frac{1}{2} + \frac{p}{2\bar{C}_{P,p}} \right]^{\frac{1}{p}} \max_{1 \leq i \leq n_z} \frac{h_{K_i} \mu_d(\omega_z)^{\frac{1}{p}}}{\mu_d(K_i)^{\frac{1}{p}} h_z}$$

and

$$C_{P,p}(\omega_z) \leq 12d\bar{C}_{P,p} \kappa_z^{\frac{d}{p}-1} \left( \frac{1}{2} + \frac{1}{2} \max\left\{ \kappa_z^{-d} K_{p,d}(\kappa_z), \frac{p}{d\bar{C}_{P,p}} \right\} \right)^{\frac{1}{p}}$$

with  $\kappa_z = \frac{3d}{2} \max_{y \in \partial\omega_z} |y - z| / \min_{y \in \partial\omega_z} |y - z|$  and

$$K_{p,d}(x) \leq \begin{cases} \frac{1}{d} \left( \frac{p-1}{|d-p|} \right)^{p-1} x^{\max\{p,d\}} & \text{if } p \neq d, \\ \frac{1}{d} (\ln x)^{d-1} & \text{if } p = d. \end{cases}$$

## Necessary Modifications

- ▶ Replace the primal norm by  $\|v\| = \left\{ \varepsilon \|\nabla \cdot\|_{L^2(\Omega)}^2 + \|\cdot\|_{L^2(\Omega)}^2 \right\}^{\frac{1}{2}}$ .
- ▶ Replace the dual norm by  $\|\cdot\|_* = \sup\{\langle \cdot, v \rangle : \|v\| = 1\}$ .
- ▶ Replace  $h_z$  by  $\min\{\varepsilon^{-\frac{1}{2}} h_z, 1\}$ .
- ▶ Replace  $c_2(\omega_z)$  by  $\max\{c_2(\omega_z), 1\}$ .